EC11 REVERSE DIRECTION SERIES SPECIFICATION

1. 一般事项General

1-1. 适用规格 Scope

本规格书适用于微小电流回路的电子设备,属11型回转型编码器.

This specification applies to 11mm size low-profile rotary encoder (incremental type) for microscopic current circuits, used in electronic equipment.

1-2. 标准状态Standard atmospheric conditions

除另有规定外,测量应在以下状态下进行:

Unless otherwise specified, the standard range of atmospheric conditions for making measurements and test is as following limits:

温 度 Ambient temperature : 15℃ to 35℃ 相对湿度 Relative humidity : 25% to 85% 气 压 Air pressure :86kpa to 106kpa

如果对在上述所提到的条件中所做的实测值有疑问的话,应使用以下条件进行测量:

If doubt arises on the decision based on the measured values under the above-mentioned conditions, the following conditions shall be employed:

温 度 Ambient temperature: 20±1℃ 相对湿度 Relative humidity : 63% to 67% 气 压 Air pressure :86kpa to 106kpa

1-3. 使用温度范围

Operating temperature range $:-30\,\mathrm{^{\circ}\!C}$ to+80 $\mathrm{^{\circ}\!C}$

1-4. 保存温度范围

Storage temperature range : -40°C to+85°C

2. 构造Construction

2-1. 尺寸 Dimensions

见所附成品图 Refer to attached drawing

3. 额定值 Rating

3-1. 额定电压

Rated voltage: DC 5V

3-2. 最大额定电流 (阻抗负载)

Maximum operating current (resistive load) 各相导线 Each lead: 0.5mA(Max 5mA; Min 0.5mA) 公共导线Common lead: 1mA(Max 10mA; Min 0.5mA)

图1 fig.1 ⊸ DC 5V $10 \text{K}\,\Omega$ 10KΩ ≤ Terminal A Terminal B A端子 B端子 -W^--**/**///_ ⊸B 10K Ω 10K Ω Encoder 0. 01 μ F ⊥ 0.01 μ F 编码器 Terminal C

4. 使用上的事项Application Notes

4-1. 避免储藏于高温潮湿及腐蚀的场所. 产品购入后尽可能在6个月内使用完. 拆包装后未使用完的剩余产品需储藏于防潮防毒的环境下.

Avoid storing the products in a place at high temperature, high humidity and in Corrosive gases. Please use this product as soon as possible with 6 months limitation. If any remainder left after packing is opened, please store it with proper moisture proofing, gasproofing etc.

- 4-2. 编码器信号的计算方法应将操作的速度,信号的取样时间及电子回路中的微电脑软体等考虑进去.
 The encoder pulses count method should be designed with taking operating speed, sampling time and esign of the microcomputer software into cosideration.
- 4-3. 此产品在定位点的输出波形参照 (5-1),因此在设计软体时请留意其状态,推荐以A相位为参考基准。
 With this products the detent position output consult fig. 5-1. Therefore make the A phase
 the reference at the soft ware design stage. Recommended that use A output signal for the reference.
- 4-4. 在设计时要考虑到杂讯, 建议使用R/C滤波电路, (图1)

At design of the pulse count process. Using the C/R filter circuit is Recommended. (fig. 1)

4-5. 本产品请勿碰触到水,可能会导致输出波形的异常.

Care must be taken not to expose this product to water or dew to prevent possible problem in pluses output waveform.

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5. 电气性能 Electrical Characteristics								
项目		条件		规格				
ITEM		CONDITIONS		SPECIFICATIONS				
	A、B两信号输出相位差,输出波形详细见(图2/3)(虚线表示带卡点装置的上擎子处位置)							
	2 Phase-different signals (signal A, signal B) Details shown in fig. 2/3>							
	(The broken line sho	ws detent positi	on.)					
	轴回转方向	信号		输出波形				
	Shaft rotati-	Signal		Output				
5-1. 输出信号	onal direction		图2 fig.2	图3 fig.3				
Output signal		A(A-C端子间)	OFF	C OFF				
format	顺时针方向	A (TerminalA-C)	ON					
	C. W	B(B-C端子间)	OFF ON	OFF ON				
		B (Termina1B-C)	OFF - I -	! — 0FF — — —				
	14 H1 F1 -> .4	A (A-C端子间)	ON	i on i l				
	逆时针方向 C.C.W	A (TerminalA-C)	0FF	OFF H				
	C. C. W	B(B-C端子间)	0N	ON] [] [
		B (Termina1B-C)		□15 个脉冲/360°(图2)				
5-2. 分解能力	回转360°的输出脉冲数	ikr		15pulses/360° (fig. 2)				
S-2. 分所 配力 Resolution	Number of pulses in			■20个脉冲/360° (图3)				
Resolution	Number of purses in	Jou Totation.		20pulses/360° (fig. 3)				
	下(图4) 所示回路, 4			20pu1303/300 (11g. 3)				
		下(图4)所示回路,轴以360°/S的速度转动测定。 Measurement shall be made under the condition as follows.						
	Shaft rotational spe		Test circuit: (fi					
		图4〈fig.4〉		图5〈fig.5〉				
			5V → OFF — ,	1 1 1				
	10ΚΩ Ş	\$ 10K	Ω 3. 5V -	A A A A -				
5-3. 开关特性	10KΩ Terminal A A 端 子 Encoder 1.5V - Encoder							
Switching								
characteristics		·	扁码器 ON V V	\				
		—o Terminal	Ct1	t2 <u>t3</u>				
		7////// C端子						
	(注)编码0FF指输出。	已压3.5V以上的状态	(fig. 5).					
	Code-OFF area	:The area which	the voltage is 3.5V	V or more(fig.5).				
	编码0N指输出电	压1.5V以下的状态	(fig. 5).					
			the voltage is 1.5	5V or less(fig. 5).				
	编码从OFF→ON或ON→O							
5-3-1. 振荡	间.应符合规定Specified by the signal's passage			t1, t3 ≤ 3mS				
Chattering	time from 1.5V to 3.		hing					
	position (code OFF ~ ON or ON ~ OFF)							
	编码0N部份的1.5V以上的电压变动时间在振荡t1,t3之							
E 2 0 海三十四	间会产生1mS以上,1.5V以下的0N部份.另外,如果各突跳							
5-3-2. 滑动杂讯	1.5V以下的范围在1mS以上时,则判定为另一个突跳.							
(突跳)Sliding	Specified by the time of voltage change exceed			t 2 ≤ 2mS				
noise (Bounce)	1.5V in code-0N area. When the bounce has code			t 2 ≺ 2 mo				
	-ON time less than 1mS between chattering (tlor t3) the voltage change shall be regarded as a part of							
	chattering. When the code-ONtime between 2 bounces is							
less than 1mS, they are regarded as 1 linked bounce.								

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5-3-3. 滑动噪音	编码0FF部份的电压变动。	3.5V以上	
Sliding noise	The voltage change in code-OFF area.	3.5Vmin	
	下(图6)所示回路,轴以360°/S的速度转动测定。		
	Measurement shall be made under the condition		
	which the shaft is rotated at 60r/min		
5-4. 相差位	1	T1、T2、T3、T4≥0.08T	
Phase	A信号(A~C间) OFF 图6 fig. 6	见图6 (fig.6)	
difference	signal A ON		
	OFF		
	B信号(B~C间)ON		
	$\begin{array}{c c} \hline signa1 & B & \hline & T_1 T_2 T_3 T_4 \\ \hline \end{array}$		
	C.W Direction		
5-5. 绝缘阻抗	在端子和支架间施加电压 250V DC。		
Insulation	Measurement shall be made under the condition	100ΜΩ 以上	
resistance	which a voltage of 250V DC is applied between	100MΩ Min	
	individual terminals and frame.		
5-6. 耐电压	在端子和支架间施加AC300V电压1分钟	不得有绝缘破坏	
Dielectric	A voltage of 300V AC shall be applied for	Without arcing or breakdown.	
strength	1 minute between individual terminals and frame.		
	出力信号处于ON时安定状态条件下测定.	10以下	
	Measurement shall be stable condition which a	1ΩMax	
	output signal is ON.		
6. 机械性能 Mecha	nical Characteristics	1	
6-1. 全回转角度		2600 (I J. H. L.)	
		360°(无止档点) 360°(Endless)	
Total ratational angle	口子口工以上上社里		
6-2. 定位点力矩	只适用于附卡点装置	$2 \sim 15$ mN. m. $(20 \sim 150$ gf. cm)	
Detent torque	Only suitable for C.C, equipment. 只适用于附卡点装置	口20上户台河原名第120 + 20	
6-3. 定位点数及位置 Number	八边州丁門下鳥表直 Only suitable for C.C, equipment.	□30点定位间隔角度12° ± 2°	
and position	only surtable for c.c, equipment.	30detents Step angle: 12° ± 2° ■20点定位间隔角度18° ± 2°	
of detent			
6-4. 轴的推拉强度	在轴端,沿轴向施加 8Kg 的静负荷力推和拉各10秒钟	20detents Step angle: 18° ± 2° 轴向虚位间隙0.4以内	
	(产品焊锡固定在PCB上。)	新角ft play in axial	
Push-pull		1	
strength of	Push and pull static load of 8Kg shall be	direction 0.4 Max	
shaf t	applied to the shaft in the axial direction for		
(10s. (After soldering of the PC board)	サファロト エハウルルコ カルカル	
6-5. 端子强度	在端子的先端施加5N(500g)的力1分钟。	端子无损坏,无过度的松动.允许变形.	
Terminal	A static load of 5N(500g) be applied to the tip of	Without damage or excessive	
strength	terminals for 1 minute in any direction.	looseness of terminals, terminal	
((4).大川仏田田田市		bend is permitted.	
6-6. 轴套螺纹紧固强度		7. 0kgf. cm以上	
Bushing Nut		7.0kgf.cm Min	
Tighten Strength		0 4 N.T	
6-7. 轴向间隙		0.4mm 以下	
Shaft play in axial		0.4mm Max	
direction	大吃食材质地SIM 从 初及石贮河花上50 N /500 C) 以	0.7.1/2000 0 5 101 = (1 12.	
(0 村田二	在距离轴顶端5MM处,沿径向瞬间施加50mN.m(500gf.cm)的	0.7*L/30mm p-p 以下 (L: 指 皮柱亚五列444年244年26)	
6-8. 轴摆动 Shoft webble	力测试	安装平面到轴的柄端的距离.)	
Shaft wobble	A momentary load of 500gf.cm should be applied at the	0.7*L/30mm p-p Max	
	point 5mm from the tip of the shaft in a direction	L: Distance between mounting surface	
(04404+45-1	perpendicular to the axis of shaft.	and measuring point on the shaft	
6-9. 轴的回转方向摆动	用角度板测定.	5°以下	
Shaft play	Testing by angle board.	5° Max	
in rotational			
wobble			

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7 耐久性能 Endur	7 耐久性能 Endurance Characteristics							
项目	条件	规格						
ITEM	CONDITIONS	SPECIFICATIONS						
	在无负荷条件下轴以600~1000周/小时速度回转,	■在力矩≤100gf.cm时30,000±200周						
	一日连续5000~8000次.	$30,000 \pm 200$ cycles per below 100gf.cm.						
	The shaft of encoder shall be rotated at a speed of	□在力矩 > 100gf.cm时15,000 ± 200周.						
7-1. 回转寿命	600~1000cycles/H without electrical load, after with	$15,000 \pm 200$ cycles per above 100 gf.cm.						
Rotational	measurements shall be made.	振荡 t1, t3≤5mS. 突跳 t2≤3mS.						
life	(5000 to 8000 continuous cycles for 24 hours.)	尚余有轻微定位感.						
		端子间接触阻抗200Ω以下						
		Chattiring t1, t3 \leq 5mS. Bounce t2 \leq 3mS.						
		Detent feeling has to remains						
		Contact resistance 200ΩMax						
	温度40±2℃,湿度90~95%的恒温恒湿槽中放置96±4	所有项应满足初期规格						
))	小时后,在常温、常湿中放置1.5小时后测试. The	Specifications in clause						
7-2. 耐湿性	encoder shall be stored at temperature of 40 $\pm 2^{\circ}$ C	all items is shall be						
Damp heat	with relative humidity of 90% to95% for96 ± 4H	satisfied.						
	in a thermostatic chamber. And the encoder shall							
	be subjected to standard atmospheric conditions							
	for 1.5H, After which measurements shall be made.							
	温度85±3℃的恒温箱中放置96±4小时,	所有项应满足初期规格。						
7-3. 耐热性	常温、常湿放置1.5小时后测试.	Specifications in clause all items is shall be						
7-3. 顺 然性 Dry heat	The encoder shall be stored at a temperature of $85 \pm 3\%$ for $96 \pm 4H$ in a thermostatic chamber. And	satisfied.						
Dry neat	then the encoder shall be subjected to standard	Satisfied.						
	atmospheric conditions for 1.5H, After which							
	measurements shall be made.							
	温度-40±3℃的恒温箱中放置96±4小时,	所有项应满足初期规格。						
	常温、常湿放置1.5小时后测试.	Specifications in clause						
	The encoder shall be stored at a temperature of	all items is shall be						
7-4. 低温特性	-40 ± 3 °C for 96 ± 4 H in a thermostatic chamber. And	satisfied.						
Cold	then the encoder shall be subjected to standard							
	atmospheric conditions for 1.5H, After which							
	measurements shall be made.							
	槽焊 Dip soldering.	不得有绝缘体的破损、变形、						
7-5. 焊锡耐热性	使用基板: t=1.6mm的单面覆铜板.	接触无异常.						
Resistance	Printed wiring board: single-sided copper clad	Electrical characteristics						
to Soldering	laminate board with thickness of 1.6mm.	shall be satisfied No						
heat	预热: 基板表面温度100℃以下, 时间1分钟以内.	mechanical abnormality.						
	Preheating: 1. Surface temperature of board: 100℃.							
	or less 2. Preheating time: within 1 minute.							
	焊接: 温度260±5℃或以下, 时间3秒以内.							
	Soldering: Solder temperature: 260 ± 5°C or less							
	Immersion time: within 3S							
	手焊 Manual soldering. 温度300℃以下,时间3秒以内.							
	Bit temperature of soldering iron: 300°C less than							
	Application time of soldering iron: within 3S							
7-6. 焊锡性	端子在260℃±5℃温度的焊锡槽内浸锡3秒±0.5秒.	浸渍面须有75%以上焊锡附着						
Solderability	The terminals shall be immersed into solder bath	A new uniform coating of						
	at 260℃ for 3S ± 0.5S.	solder shall cover75% minimum						
		of the surface being immersed.						

EC11 REVERSE DIRECTION SERIES SPECIFICATION

推动开关部分Push Switch Portion

备注: 以下规格适用于RE11编码器带开关系列.

Note: The following specification is only suitable for the one type with switch construction of RE11 encoder series.

1. 额定值 Rating

1-1. 额定电压

Rated voltage: DC 5V

1-2. 最大额定电流(阻抗负载)					
Maximum operat	ing current (resistive	e load):10mA Max				
2. 电气性能 Electi	rical Characteris	tics				
项目		条件		规格		
ITEM	CONDITIONS			SPECIFICATIONS		
2-1.接触电阻	用DC 5V 1mA 电压测定	用DC 5V 1mA 电压测定.			$\leq 100 \text{m}\Omega$	
Contact	Voltage test at DC	5V 1mA.	100mΩor less			
resistance						
2-2. 绝缘阻抗	在端子和安装板间施加	电压 250V DC.				
Insulation	Measurement shall be	made under the	condition	100ΜΩ 以上		
resistance	which a voltage of 2	50V DC is applie	d between	100MΩ Min		
	individual terminals and bushing and plank.					
2-3. 振荡	以1秒钟1往返(0FF-0N-	0FF)按压动作.	≤ 10mS			
Bouncing	Shaft shall be push	at 1 cycles/s(OF	F-0N-0FF)	10mS or less		
2-4. 耐电压	在端子和安装板间施加	AC300V电压1分钟		不得有绝缘破坏		
Dielectric	A voltage of 300V AC shall be applied for 1 minute			Without arcing or breakdown.		
strength	between individual terminals and bushing and plank.					
3 机械性能 Mecha	nnical Characterist	ics				
3-1. 开关电路				单极单投(按压ON)		
接点数					Single pole and single throw	
Switch circuit and				(push ON)		
number of pulse						
3-2. 开关动作力	在轴端,沿轴向施加的	按压力.				
Operation	Push static load to	the shaft in the	axial	$500 \pm 200 \mathrm{gf}$		
fore of switch	direction					
3-3. 开关移动量					\blacksquare 0. 5 ± 0. 3 mm	
Travel of switch				\square 1. 5 ± 0. 5 mm		
4 耐久性能 Endura	ance Characteristi	cs				
	在无负荷条件下沿轴向施以1Kgf以下的力,以600次/小时			■20,000±200次.(0.5行程)		
	的速度按压。			$20,000 \pm 200 \text{cycles.}$ (0.5 Travel)		
	Push 1Kgf to the shaft of encoder in the axial			□15,000±200次.(1.5行程)		
4-1. 按压寿命	direction under non-	direction under non-load conditions, and with a speed			15,000 ± 200cycles. (1.5 Travel)	
Push-life	of 600 times/hour.				接触电阻: ≤200mΩ. 其它应满足初期规格.	
				Contact resistance: $200m\Omega$ or less. Specification in clause shall be satisfied.		
受控编号 Document No	修订 Revision	日期 Date	经 办 Designed	审 核 Check	批 准 Approved	
	初始发行	2011-1-4		, , ,		
文号 File No	***************************************					
EC11带定位反向专用						
版 ★ VEDCION: AO						